

HART® Field Device Specification:
EUROMAG, MC608A



TABLE OF CONTENTS

Table of Contents	2
1. Introduction.....	3
1.1 Scope.....	3
1.2 Purpose.....	3
1.3 Who should use this document?	3
1.4 Abbreviations and definitions	3
1.5 References.....	3
2. Device Identification.....	4
3. Product Overview	4
4. Product Interfaces	4
4.1 Process Interface	4
4.1.1 Sensor Input	4
4.2 Host interface	5
4.2.1 Analog Output 1: 4-20mA	5
5. Device Variables.....	5
6. Dynamic Variables.....	6
6.1 Burst Mode.....	7
6.2 Catch Device Variable	7
6.3 Busy and Delayed Response	7
6.4 Long Messages.....	7
6.5 Non-Volatile Memory.....	7
6.6 Modes.....	7
6.7 Write Protection	7
6.8 Damping.....	7
6.9 Device Description Structure	8
Annex A. Capability Checklist.....	14
Annex B. Default Configuration	15

1. INTRODUCTION

1.1 Scope

The EUROMAG EMF, complies with HART Protocol Revision 7.4. This document specifies all the device specific features and documents HART Protocol implementation details (e.g., the Engineering Unit Codes supported).

1.2 Purpose

This specification is designed to complement the MC608 Installation Manual by providing a complete, unambiguous description of this Field Device from a HART Communication perspective

1.3 Who should use this document?

The specification is designed to be a technical reference for HART End Users. This document assumes the reader is familiar with HART Protocol requirements and terminology.

1.4 Abbreviations and definitions

EMF	Electromagnetic Flow Meter
ADC	Analog to Digital Converter
CPU	Central Processing Unit (of microprocessor)
DAC	Digital to Analog Converter
EEPROM	Electrically-Erasable Read-Only Memory
ROM	Read-Only Memory

1.5 References

HART Smart Communications Protocol Specification. HCF_SPEC-12. Available from the HCF.

Euromag MC608, Installation Manual

2. DEVICE IDENTIFICATION

Manufacturer Name:	Euromag International S.r.l.	Model Name(s):	MC608
Manufacture ID Code:	24710 (0x6086)	Device Type Code:	58011 (0xE29B)
HART Protocol Revision	7.4	Device Revision:	1
Number of Device Variables	12		
Physical Layers Supported	FSK		
Physical Device Category	Electromagnetic flow meter		

3. PRODUCT OVERVIEW



The EUROMAG, MC608 A is a converter that has been designed with the purpose of meeting all the requirements of modern water management systems.

4. PRODUCT INTERFACES

4.1 Process Interface

4.1.1 Sensor Input

The sensor input is a Mag flow sensor.

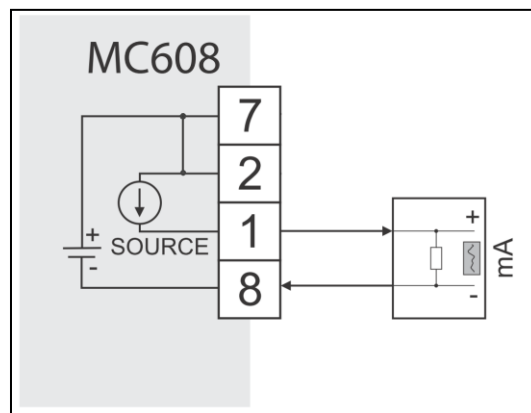
4.2 Host interface

4.2.1 Analog Output 1: 4-20mA

The HART Communication is supported on active two-wire 4-to-20mA current loop .

	Values (percent of range)	Values (mA or V)
Maximum current	100%	20.0 mA
Minimum current	0.00%	4 mA
Multi-Drop current draw		4.0 mA
Lift-off voltage		9 VDC (@250Ohm)
Loop resistance range		230 - 800 Ohm

Figure 1 – Electrical connections



5. DEVICE VARIABLES

Table 2 - Device Variables

Num	Name	Unit Codes: default
0	Volume flow	m ³ /s
1	Flow velocity	m/s
2	Mass flow	kg/s
3	Totalized positive volume	m ³
4	Totalized negative volume	m ³
5	Partial positive volume	m ³
6	Partial negative volume	m ³
7	pressure	Bar (Fixed)
8	temperature	DegC
244	% of range	
245	Loop Current	mA (39)
246	PV	
247	SV	
248	TV	
249	FV	

6. DYNAMIC VARIABLES

Four Dynamic Variables are supported.

The assignment to Dynamic Variables is mappable except for PV:

Table 3 - Dynamic Variables

Num	Name
PV	Volume flow m3/s
SV	Any dynamic variable (0-8)
TV	Any dynamic variable (0-8)
FV	Any dynamic variable (0-8)

6.1 Burst Mode

The MC608 does not support Burst Mode.

6.2 Catch Device Variable

The MC608 does not support Catch Device Variable.

6.3 Busy and Delayed Response

Busy response is not used.

Delayed-response is not used.

6.4 Long Messages

Not supported.

6.5 Non-Volatile Memory

EEPROM is used to hold the device's configuration parameters. New data is written to this memory immediately on execution of a write command.

6.6 Modes

Fixed current mode is supported.

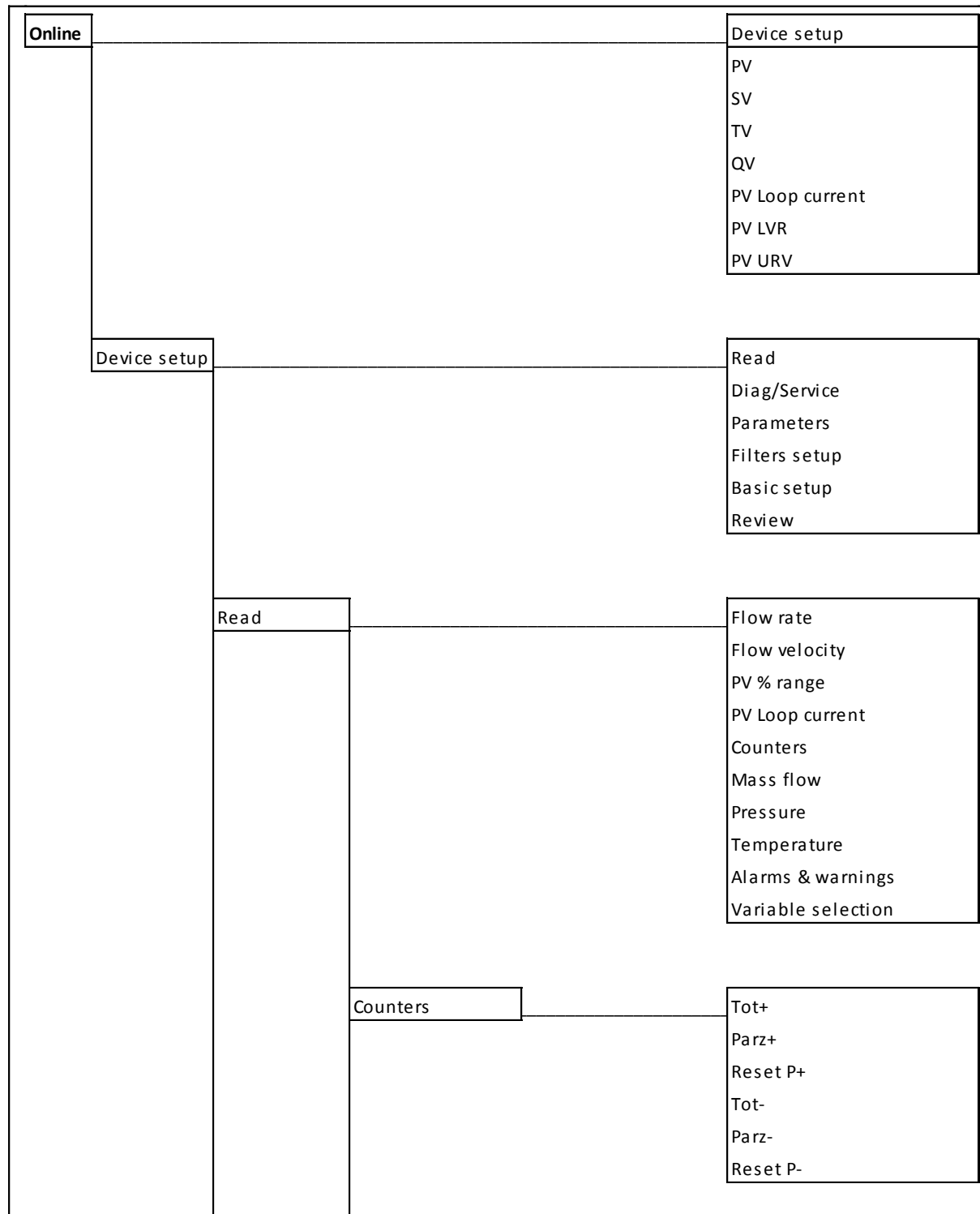
6.7 Write Protection

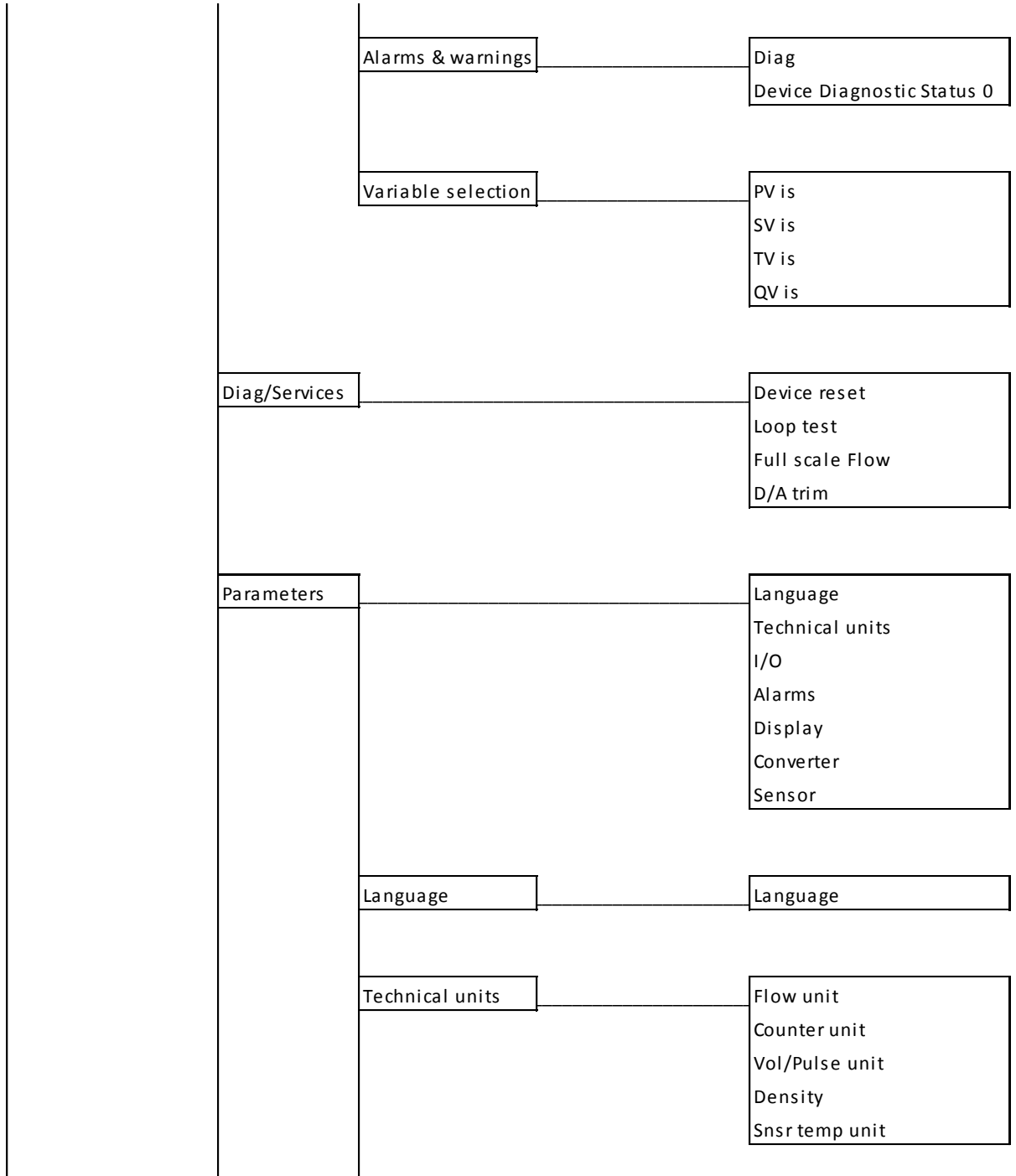
Write protection is not supported.

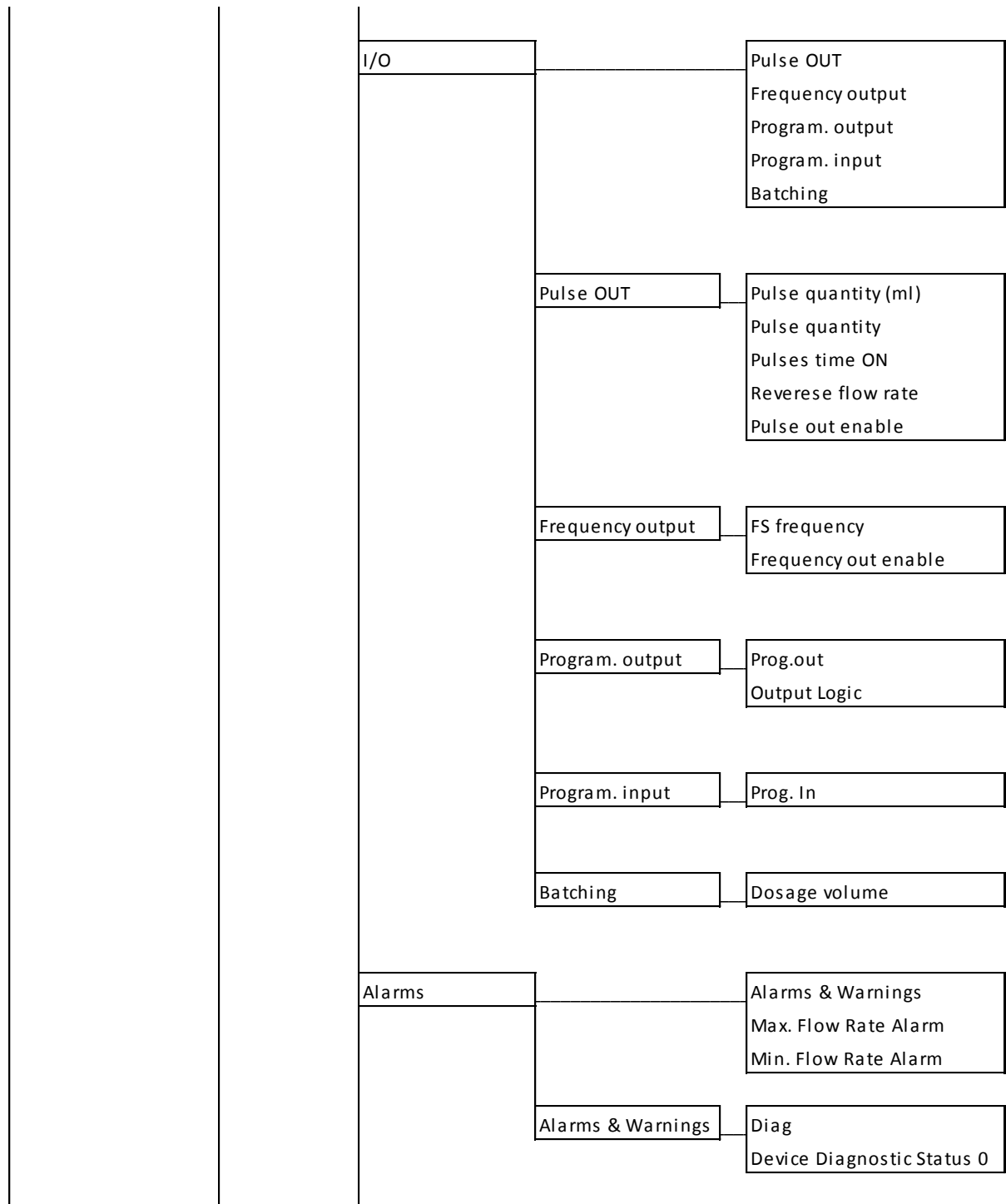
6.8 Damping

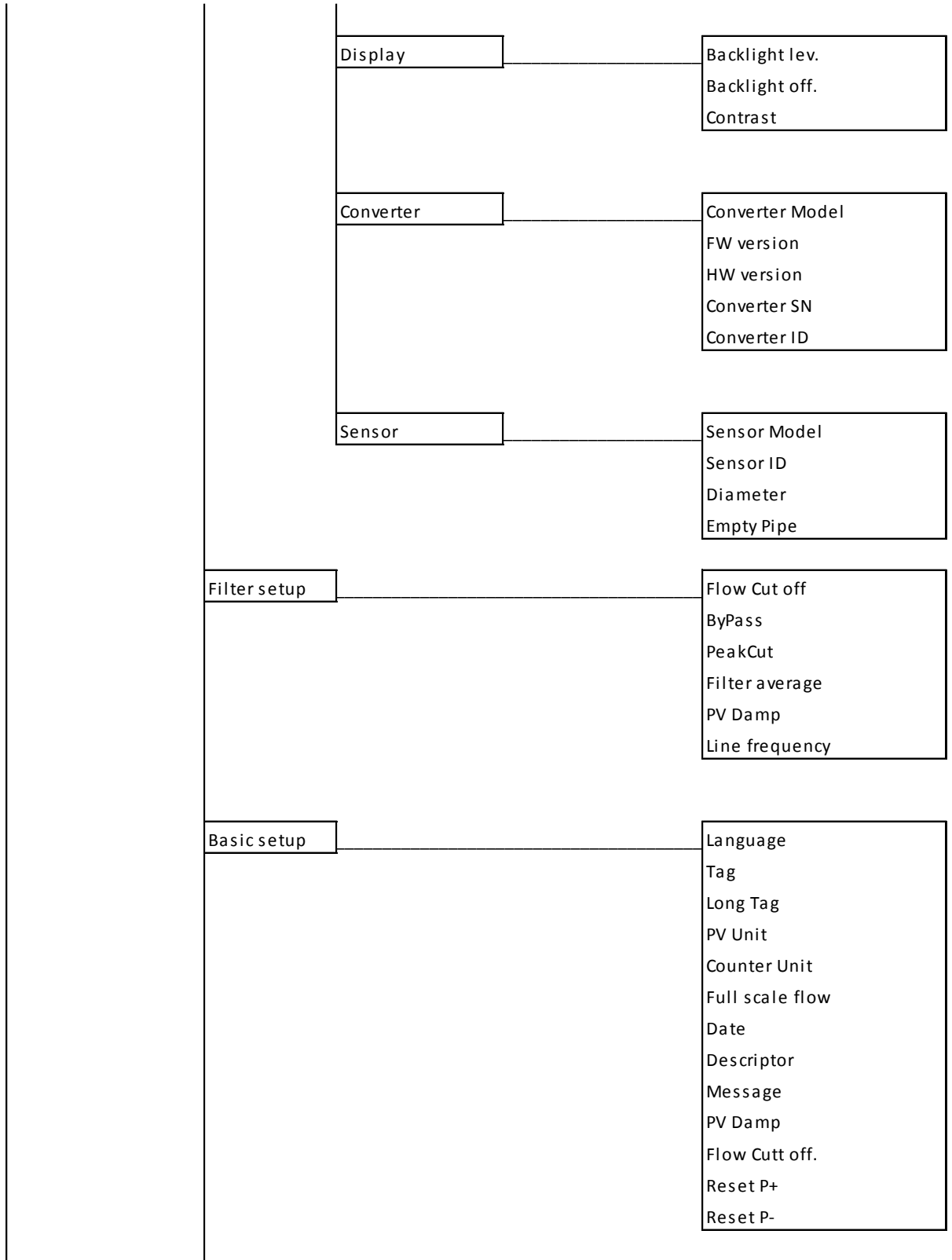
Damping is standard, affecting only the PV and the loop current signal. Damping is adjustable from 0 to 60 seconds.

6.9 Device Description Structure









Review

Manufacturer
Model
Distributor
Write protect
Dev id
Cfg chng count
Max dev vars
Tag
Long tag
Descriptor
Message
Date
Final asmbly num
Universal rev.
Fld dev rev.
Software rev.
Poll addr
Loop current mode
Num req preams.
Num resp preams.
PV Unit
PV % rng
PV Xfer fnctn
PV LRV
PV URV
Flow Cut off
PV Damp
ByPass
PeakCut
Filter average
Damping-averaging time
Line frequency
Converter model
Converter SN
FW version
HW version

Sensor model
Sensor ID
Diameter
Empty Pipe
Language
Max.Flow Rate Alarm
Min. Flow Rate Alarm
Pulses quantity
Pulses time ON
Reverse flow rate
Pulses out enable
FS frequency
Prog.out
Prog.in
Dosage volume
Backlight lev.
Backlight off.
Contrast

ANNEX A. CAPABILITY CHECKLIST

Manufacturer, model and revision	EUROMAG, MC608
Device type	Electromagnetic flow meter
HART revision	7.4
Device Description available	Yes
Number and type of sensors	1
Number and type of actuators	0
Number and type of host side signals	1: 4-20 mA analog/HART
Number of Device Variables	12
Number of Dynamic Variables	4
Mappable Dynamic Variables	YES
Alternative operating modes	NO
Burst mode	NO
Fixed current mode	YES
Write-protection	NO

ANNEX B. DEFAULT CONFIGURATION

Parameter	Default value
Write protect	off
Transfer function	Linear
Number of response preambles	5